



## From Multi-Sensing to Symbolic Representation for Robotic Manipulation Tasks

May 9th, 2011 at ICRA 2011

[Check out the Call for Papers here.](#)

### Submission Deadline: March 1st, 2011

In this workshop we shall cover representations underlying the human strategies that define the appropriate characteristics of the grasp and manipulation movements in specific contexts or objects and how these strategies can be extended and replicated by robots.

The 2011 IEEE International Conference on Robotics and Automation (ICRA 2011) will take place from May 9 to 13, 2011 at the Shanghai International Conference Center and the Shangri-La Hotel Shanghai Pudong in Shanghai, **China**.

[Check the Workshop Homepage here.](#)